

> restart:

We load our package:

> with(IntegrableConnections);

[Eigenring, Evalm, G_matrix, G_matrix0, HyperexponentialSolutions, Id, Mapply, MatrixColumnPrimpart, MatrixColumnPrimpartRat, Mexpsolde, Mpolsolde, Mratsolde, Msylvester, Mylinsolve, NNIexponents, PolynomialSolutions, RationalSolutions, Reduction, TestIntegrabilityConditions, Trigonalize, backsups, candidates, col_pval, colechelon, colval, complement, convert_back, denomatrix, denomvector, direct_ratsol, eval_block_reduced, evalam, exp_parts, formal_reduce, gen_sylvester, getargs, good_form, intDiff, int_diff_split, l_colechelon, l_column_rank, l_moser_reduce, l_qtcd, l_super, l_super_reduce, lc_evala, lc_evalam, localize, log_collect, log_free, mat_block_reduce, mat_change_exp_part, mat_check, mat_coeff, mat_colvaluation, mat_convert, mat_copy, mat_difference, mat_eval, mat_get_dim, mat_get_exp_part, mat_get_ext, mat_get_indicial_polynomial, mat_get_inv_transformation, mat_get_order, mat_get_ramification, mat_get_terms, mat_get_transformation, mat_get_type, mat_lc, mat_lead_mon, mat_product, mat_pval, mat_subs, mat_sum, mat_swap, mat_to_simple, mat_tools, mat_transform, mat_val, mat_valuation, matrix_series, matval, minimalIntegerRoot, mult, my_linsolve, mydegree, myequaind, new_matrix, newton, newton_polygon, nonzero, normalm, pencil_block_reduce, pencil_solve, pgaussUnimod, poly_pval, poly_sols, poly_val, prank, pval, qtcd, ramified_case, ramified_reduction, randomMatrix, randomPoly, randomRat, ratsuper, reduceColRank4, reg_sols, regular_series, remove, rowechelon, seq_evala, sim_sylvester, simple_eval, simple_sols, sortColumns, super_form, system_expsolde, tensor_prod, transform, truncate, utils, val, vall, val_ldegree, valuation, vectdegree]

(1)

The library linalg is also needed.

> with(linalg):

We load OreModules in order to use the procedure to write a D-finite partial differential system to an integrable connection.

> with(OreModules):

BrycLetac system in dimension 2 - Gaussian Case

We define the OreAlgebra (needed for OreModules):

> Alg2:=DefineOreAlgebra(diff=[d1,x1],diff=[d2,x2],polynom=[x1,x2],comm=[d,a]):

We give the equations of the system:

> R2 := matrix(2,1,[-(1/2)*d*d2+d1^2-x2*d2^2,2*d1*d2+x1*d2^2]);

$$R2 := \begin{bmatrix} -\frac{1}{2} d d2 + d1^2 - x2 d2^2 \\ 2 d1 d2 + x1 d2^2 \end{bmatrix}$$

(2)

We write the system as an integrable connection:

> **C2:=OreModules[Connection](R2,Alg2);**

$$C2 := \left[\begin{array}{cccc} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -\frac{1}{2} x1 \\ 0 & \frac{1}{2} d & 0 & x2 \\ 0 & 0 & 0 & \frac{(-3-d)x1}{-4x2+x1^2} \end{array} \right], \left[\begin{array}{c} 0 \ 1 \ 0 \ 0 \\ 0 \ 0 \ 0 \ 1 \\ 0 \ 0 \ 0 \ -\frac{1}{2} x1 \\ 0 \ 0 \ 0 \ \frac{6+2d}{-4x2+x1^2} \end{array} \right] \quad (3)$$

If we want to know the basis of the associated module in which the connection is written, we can use the procedure KBasis of OreModules:

> **OreModules[KBasis](R2,Alg2);**

$$\left[\lambda_1, \lambda_1 d2, d1 \lambda_1, \lambda_1 d2^2 \right] \quad (4)$$

We define the right-hand sides of the connection.

> **b1:=vector(4,[0,0,1,0]);**
b2:=vector(4,[0,0,0,0]);

$$b1 := \left[0 \ 0 \ 1 \ 0 \right]$$

$$b2 := \left[0 \ 0 \ 0 \ 0 \right] \quad (5)$$

We use our procedures for computing rational solutions of the integrable connection. The right-hand sides are given as last input.

> **RationalSolutions(C2,[x1,x2],['param' , [d] , 'rhs' , [b1,b2]]);**

$$\left[\left[\begin{array}{cccc} \frac{1}{2} x1^2 d + 2 x2 x1 & 1 & & \\ 2 & 0 & 0 & \\ x1 d & 1 & 0 & \\ 0 & 0 & 0 & \end{array} \right], \left[\begin{array}{c} \frac{1}{2} x1^2 \\ 0 \\ x1 \\ 0 \end{array} \right] \right] \quad (6)$$

The output contains a matrix whose columns form a basis of rational solutions of the homogeneous integrable connection and a vector that is a particular solution of the non-homogeneous integrable connection. A solution is then given by the sum of a linear combination of the columns of the matrix and the vector.

BrycLetac system in dimension 3 - Gaussian Case

We define the OreAlgebra (needed for OreModules):

> **Alg3:=DefineOreAlgebra(diff=[d1,x1],diff=[d2,x2],diff=[d3,x3],
 polynom=[x1,x2,x3],comm=[d]);**

We give the equations of the system:

> **R3 := matrix(3,1,[-d*d2+d1^2-x2*d2^2-2*x3*d2*d3,-(1/2)*d*d3+2*d1*d2+x1*d2^2-x3*d3^2,2*d1*d3+d2^2+2*x1*d2*d3+x2*d3^2]);**

$$R3 := \begin{bmatrix} -d d2 + d1^2 - x2 d2^2 - 2 x3 d2 d3 \\ -\frac{1}{2} d d3 + 2 d2 d1 + x1 d2^2 - x3 d3^2 \\ 2 d1 d3 + d2^2 + 2 x1 d2 d3 + x2 d3^2 \end{bmatrix} \quad (7)$$

We write the system as an integrable connection:

> C3:=OreModules[Connection](R3,Alg3):

If we want to know the basis of the associated module in which the connection is written, we can use the procedure KBasis of OreModules:

> OreModules[KBasis](R3,Alg3);

$$[\lambda_1, \lambda_1 d3, \lambda_1 d2, \lambda_1 d1, \lambda_1 d3^2, \lambda_1 d2 d3, \lambda_1 d1 d3, d3^3 \lambda_1] \quad (8)$$

We define the right-hand sides:

> b1:=vector(8,[0\$3,1,0\$4]);

b2:=vector(8,[0\$8]);

b3:=eval(b2);

$$b1 := [0 \ 0 \ 0 \ 1 \ 0 \ 0 \ 0 \ 0]$$

$$b2 := [0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0]$$

$$b3 := [0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0] \quad (9)$$

We use our procedure for computing rational solutions of the integrable connection:

> RationalSolutions(C3,[x1,x2,x3],['rhs ', [b1,b2,b3], 'param', [d]]);

$$\begin{bmatrix} \frac{1}{6} x1^3 d^2 + x1 d x2 + 4 x3 & \frac{1}{2} x1^2 d + x2 & x1 & 1 \\ 4 & 0 & 0 & 0 \\ x1 d & 1 & 0 & 0 \\ \frac{1}{2} x1^2 d^2 + d x2 & x1 d & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} \frac{1}{2} x1^2 \\ 0 \\ 0 \\ x1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad (10)$$

The output contains a matrix whose columns form a basis of rational solutions of the homogeneous integrable connection and a vector that is a particular solution of the non-homogeneous integrable connection. A solution is then given by the sum of a linear combination of the columns of the matrix and the vector.