

```
> restart:
```

```
We load our package:
```

```
> with(IntegrableConnections);
```

```
[Eigenring, Evalm, G_matrix, G_matrix0, HyperexponentialSolutions, Id, Mapply,  
MatrixColumnPrimpart, MatrixColumnPrimpartRat, Mexpsolde, Mpolsolde, Mratsolde,  
Msylvester, Mylinsolve, NNIexponents, PolynomialSolutions, RationalSolutions, Reduction,  
TestIntegrabilityConditions, Trigonalize, backsups, candidates, col_pval, colechelon, colval,  
complement, convert_back, denomatrix, denomvector, direct_ratsol, eval_block_reduced,  
evalam, exp_parts, formal_reduce, gen_sylvester, getargs, good_form, intDiff, int_diff_split,  
l_colechelon, l_column_rank, l_moser_reduce, l_qtcd, l_super, l_super_reduce, lc_evala,  
lc_evalam, localize, log_collect, log_free, mat_block_reduce, mat_change_exp_part,  
mat_check, mat_coeff, mat_colvaluation, mat_convert, mat_copy, mat_difference, mat_eval,  
mat_get_dim, mat_get_exp_part, mat_get_ext, mat_get_indicial_polynomial,  
mat_get_inv_transformation, mat_get_order, mat_get_ramification, mat_get_terms,  
mat_get_transformation, mat_get_type, mat_lc, mat_lead_mon, mat_product, mat_pval,  
mat_subs, mat_sum, mat_swap, mat_to_simple, mat_tools, mat_transform, mat_val,  
mat_valuation, matrix_series, matval, minimalIntegerRoot, mult, my_linsolve, mydegree,  
myequaind, new_matrix, newton, newton_polygon, nonzero, normalm, pencil_block_reduce,  
pencil_solve, pgaussUnimod, poly_pval, poly_sols, poly_val, prank, pval, qtcd,  
ramified_case, ramified_reduction, randomMatrix, randomPoly, randomRat, ratsuper,  
reduceColRank4, reg_sols, regular_series, remove, rowechelon, seq_evala, sim_sylvester,  
simple_eval, simple_sols, sortColumns, super_form, system_expsolde, tensor_prod,  
transform, truncate, utils, val, vall, val_ldegree, valuation, vectdegree]
```

(1)

```
The library linalg is also needed.
```

```
> with(linalg):
```

```
We load OreModules in order to use the procedure to write a D-finite partial differential system as an  
integrable connection.
```

```
> with(OreModules):
```

Consider Example 3.2 in Z. Li, F. Schwarz, and S. Tsarev. Factoring systems of pde's with finite-dimensional solution space, *Journal of Symbolic Computation*, 36:443--471, 2003.

```
We define the OreAlgebra (needed for OreModules):
```

```
> Alg:=DefineOreAlgebra(diff=[d1,x1],diff=[d2,x2],polynom=[x1,x2],  
comm=[]):
```

```
We give the equations of the system:
```

```
> R:=matrix(2,1,[d1^3+(x2^2+6*x1^2-6*x1*x2)/(2*x1^3-x2*x1^2)*d1^2,  
d2^3+(3*x1-2*x2)/(x1^2-x1*x2)*d2^2+(2*x1-x2)/(x1^3-x1^2*x2)*d2]);
```

(2)

$$R := \begin{bmatrix} d1^3 + \frac{(x2^2 + 6 x1^2 - 6 x1 x2) d1^2}{2 x1^3 - x2 x1^2} \\ d2^3 + \frac{(3 x1 - 2 x2) d2^2}{x1^2 - x1 x2} + \frac{(2 x1 - x2) d2}{x1^3 - x2 x1^2} \end{bmatrix} \quad (2)$$

We write the system as an integrable connection:

> C:=OreModules[Connection](R,Alg);

$$C := \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & \frac{-x1^2 + 3 x1 x2 - x2^2}{x1^3 - x2 x1^2} & 0 & \frac{x2}{x1 - x2} \\ 0 & \frac{2 x2 x1^2 - 5 x1 x2^2 + 2 x2^3}{x1^4 - x1^3 x2} & 0 & \frac{-2 x1 x2^2 + x2^3}{x1^3 - x2 x1^2} \\ 0 & \frac{2}{x1^2} & 0 & \frac{x2}{x1^2} \end{bmatrix}, \quad (3)$$

$$\begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & \frac{-x1^2 + 3 x1 x2 - x2^2}{x1^3 - x2 x1^2} & 0 & \frac{x2}{x1 - x2} \\ 0 & \frac{-2 x1 + x2}{x1^3 - x2 x1^2} & 0 & \frac{-3 x1 + 2 x2}{x1^2 - x1 x2} \end{bmatrix}$$

If we want to know the basis of the associated module in which the connection is written, we can use the procedure KBasis of OreModules:

> OreModules[KBasis](R,Alg);

$$[\lambda_1, d2 \lambda_1, \lambda_1 d1, d2^2 \lambda_1] \quad (4)$$

We use our procedure for computing rational solutions of the integrable connection:

> RatSols:=RationalSolutions(C,[x1,x2]);

$$RatSols := \begin{bmatrix} x1 & 1 \\ 0 & 0 \\ 1 & 0 \\ 0 & 0 \end{bmatrix} \quad (5)$$

The rational solutions are given by the columns of the previous matrix. This means the original system admits two non-zero rational solutions given by 1 and x1.

Consider Example 3.3 in Z. Li, F. Schwarz, and S. Tsarev. *Factoring systems of pde's with finite-*

dimensional solution space,
Journal of Symbolic Computation, 36:443--471, 2003.

We define the OreAlgebra (needed for OreModules):

```
> Alg:=DefineOreAlgebra(diff=[d1,x1],diff=[d2,x2],diff=[d3,x3],
  polynom=[x1,x2,x3],comm=[]):
```

We give the equations of the system:

```
> R:=matrix(3,1,[d1^2-x1/(x1-1)*d1+1/(x1-1),d2+x1/(x2*(x1*x2-x2))*d1-
  x1/(x2*(x1*x2-x2)),d3-(2*x1*x3+1/2*x1)/(x1*x3-x3)*d1+(2*x3+1/2*x1)/
  (x1*x3-x3)]);
```

$$R := \begin{bmatrix} d1^2 - \frac{x1 d1}{x1 - 1} + \frac{1}{x1 - 1} \\ d2 + \frac{x1 d1}{x2 (x1 x2 - x2)} - \frac{x1}{x2 (x1 x2 - x2)} \\ d3 - \frac{\left(2 x1 x3 + \frac{1}{2} x1\right) d1}{x1 x3 - x3} + \frac{2 x3 + \frac{1}{2} x1}{x1 x3 - x3} \end{bmatrix} \quad (6)$$

We write the system as an integrable connection:

```
> C:=OreModules[Connection](R,Alg):
```

If we want to know the basis of the associated module in which the connection is written, we can use the procedure KBasis of OreModules:

```
> OreModules[KBasis](R,Alg);
```

$$[\lambda_1, d3 \lambda_1] \quad (7)$$

We use our procedure for computing rational solutions of the integrable connection:

```
> RatSols:=RationalSolutions(C,[x1,x2,x3]);
```

$$RatSols := \{ \} \quad (8)$$

The system does not admit any non-zero rational solution.

Consider Example 3.4 in Z. Li, F. Schwarz, and S. Tsarev. *Factoring systems of pde's with finite-dimensional solution space*,
Journal of Symbolic Computation, 36:443--471, 2003.

We define the OreAlgebra (needed for OreModules):

```
> Alg:=DefineOreAlgebra(diff=[d1,x1],diff=[d2,x2],diff=[d3,x3],
  polynom=[x1,x2,x3],comm=[]):
```

We give the equations of the system:

```
> v:=x1^2-x1*x3+x2^2+2*x2*x3+x3^2;
```

$$v := x1^2 - x1 x3 + x2^2 + 2 x2 x3 + x3^2 \quad (9)$$

```
> w:=-2*x2^4-8*x3*x2^3-12*x2^2*x3^2-8*x2*x3^3+2*x1*x3^3+2*x1^3*x2-3*
  x1^2*x3^2-4*x1^2*x2*x3-2*x3^4+x1^4+2*x1*x2*x3^2;
```

$$w := -2 x2^4 - 8 x3 x2^3 - 12 x2^2 x3^2 - 8 x2 x3^3 + 2 x1 x3^3 + 2 x1^3 x2 - 3 x1^2 x3^2 - 4 x1^2 x2 x3 - 2 x3^4 + x1^4 + 2 x1 x2 x3^2 \quad (10)$$

```

> R:=matrix(4,1,[
x1*v*d1-x2*v*d2+x1*(2*x1*x2+x1*x3+x2^2)*d3-2*x1*x2-x1*x3+x1^2,
x1*(x1-x3)*(2*x2-x1+2*x3)*d3+(x2+x3)^2*v*d2+2*x1*v*d2+x1*(-2*x2+
x1-2*x3),
(x2+x3)^2*v*d2*d3+x1*v*d2+2*x1*(x2+x3)*(x1-x3)*d3-2*x1*(x2+x3),
(x2+x3)^2*(x1-x3)*v*d3^2+w*d3-2*x1*x2^2-2*x1^2*x2-2*x1*x2*x3-x1^3-
x3*x1^2
]);

```

$$R := \begin{bmatrix}
[x1(x1^2 - x1x3 + x2^2 + 2x2x3 + x3^2)d1 - x2(x1^2 - x1x3 + x2^2 + 2x2x3 + x3^2)d2 + x1(2x1x2 + x1x3 + x2^2)d3 - 2x1x2 - x1x3 + x1^2], \\
[x1(x1 - x3)(2x2 - x1 + 2x3)d3 + (x2 + x3)^2(x1^2 - x1x3 + x2^2 + 2x2x3 + x3^2)d2^2 + 2x1(x1^2 - x1x3 + x2^2 + 2x2x3 + x3^2)d2 + x1(-2x2 + x1 - 2x3)], \\
[(x2 + x3)^2(x1^2 - x1x3 + x2^2 + 2x2x3 + x3^2)d2d3 + x1(x1^2 - x1x3 + x2^2 + 2x2x3 + x3^2)d2 + 2x1(x2 + x3)(x1 - x3)d3 - 2x1(x2 + x3)], \\
[(x2 + x3)^2(x1 - x3)(x1^2 - x1x3 + x2^2 + 2x2x3 + x3^2)d3^2 + (-2x2^4 - 8x3x2^3 - 12x2^2x3^2 - 8x2x3^3 + 2x1x3^3 + 2x1^3x2 - 3x1^2x3^2 - 4x1^2x2x3 - 2x3^4 + x1^4 + 2x1x2x3^2)d3 - 2x1x2^2 - 2x2x1^2 - 2x1x2x3 - x1^3 - x3x1^2]
\end{bmatrix} \quad (11)$$

We write the system as an integrable connection:

```

> C:=OreModules[Connection](R,Alg):

```

If we want to know the basis of the associated module in which the connection is written, we can use the procedure KBasis of OreModules:

```

> OreModules[KBasis](R,Alg);

```

$$[\lambda_1, d3\lambda_1, d2\lambda_1] \quad (12)$$

We use our procedure for computing rational solutions of the integrable connection:

```

> RatSols:=RationalSolutions(C,[x1,x2,x3]);

```

$$RatSols := \begin{bmatrix} \frac{1}{x1 - x3} \\ \frac{1}{(x1 - x3)^2} \\ 0 \end{bmatrix} \quad (13)$$

The system admits one non-zero rational solution, namely $1/(x1-x3)$.

Consider Example 4.1 in Z. Li, F. Schwarz, and S. Tsarev. *Factoring systems of pde's with finite-dimensional solution space*, *Journal of Symbolic Computation*, 36:443--471, 2003.

We define the OreAlgebra (needed for OreModules):

```

> Alg:=DefineOreAlgebra(diff=[d1,x1],diff=[d2,x2],diff=[d3,x3],
polynom=[x1,x2,x3],comm=[ ]):

```

We give the equations of the system (be careful there is a typo in the fifth equation in the paper):

```

> R:=matrix(6,2,[

```

```
(x1*x3-x1*x2)+(x1*x2-1)*d2+(1-x1*x3)*d3,0,(x2*x3-x1*x2)+(x1*x2-1)*
d1+(1-x2*x3)*d3,0,-x2*x3,d1-x2*x3,-x1*x3,d2-x1*x3,d3^2-(x1*x2+1)*
d3+x1*x2,0,-x1*x2,d3-x1*x2
]);
```

$$R := \begin{bmatrix} x1 x3 - x1 x2 + (x1 x2 - 1) d2 + (1 - x1 x3) d3 & 0 \\ x2 x3 - x1 x2 + (x1 x2 - 1) d1 + (1 - x2 x3) d3 & 0 \\ & -x2 x3 & d1 - x2 x3 \\ & -x1 x3 & d2 - x1 x3 \\ & d3^2 - (x1 x2 + 1) d3 + x1 x2 & 0 \\ & -x1 x2 & d3 - x1 x2 \end{bmatrix} \quad (14)$$

We write the system as an integrable connection:

```
> C:=OreModules[Connection](R,Alg);
```

$$C := \left[\begin{bmatrix} x2 x3 & 0 \\ x2 x3 & x2 x3 \end{bmatrix}, \begin{bmatrix} x1 x3 & 0 \\ x1 x3 & x1 x3 \end{bmatrix}, \begin{bmatrix} x1 x2 & 0 \\ x1 x2 & x1 x2 \end{bmatrix} \right] \quad (15)$$

If we want to know the basis of the associated module in which the connection is written, we can use the procedure KBasis of OreModules:

```
> OreModules[KBasis](R,Alg);
```

$$[\lambda_1, \lambda_2] \quad (16)$$

We use our procedure for computing rational solutions of the integrable connection:

```
> RatSols:=RationalSolutions(C,[x1,x2,x3]);
```

$$RatSols := \{ \} \quad (17)$$

The system does not admit any non-trivial rational solution.