

```
> restart:
```

```
We load our package:
```

```
> with(IntegrableConnections);
```

```
[Eigenring, Evalm, G_matrix, G_matrix0, HyperexponentialSolutions, Id, Mapply,  
MatrixColumnPrimpart, MatrixColumnPrimpartRat, Mexpsolde, Mpolsolde, Mratsolde,  
Msylvester, Mylinsolve, NNIexponents, PolynomialSolutions, RationalSolutions, Reduction,  
TestIntegrabilityConditions, Trigonalize, backsups, candidates, col_pval, colechelon, colval,  
complement, convert_back, denomatrix, denomvector, direct_ratsol, eval_block_reduced,  
evalam, exp_parts, formal_reduce, gen_sylvester, getargs, good_form, intDiff, int_diff_split,  
l_colechelon, l_column_rank, l_moser_reduce, l_qtcd, l_super, l_super_reduce, lc_evala,  
lc_evalam, localize, log_collect, log_free, mat_block_reduce, mat_change_exp_part,  
mat_check, mat_coeff, mat_colvaluation, mat_convert, mat_copy, mat_difference, mat_eval,  
mat_get_dim, mat_get_exp_part, mat_get_ext, mat_get_indicial_polynomial,  
mat_get_inv_transformation, mat_get_order, mat_get_ramification, mat_get_terms,  
mat_get_transformation, mat_get_type, mat_lc, mat_lead_mon, mat_product, mat_pval,  
mat_subs, mat_sum, mat_swap, mat_to_simple, mat_tools, mat_transform, mat_val,  
mat_valuation, matrix_series, matval, minimalIntegerRoot, mult, my_linsolve, mydegree,  
myequaind, new_matrix, newton, newton_polygon, nonzero, normalm, pencil_block_reduce,  
pencil_solve, pgaussUnimod, poly_pval, poly_sols, poly_val, prank, pval, qtcd,  
ramified_case, ramified_reduction, randomMatrix, randomPoly, randomRat, ratsuper,  
reduceColRank4, reg_sols, regular_series, remove, rowechelon, seq_evala, sim_sylvester,  
simple_eval, simple_sols, sortColumns, super_form, system_expsolde, tensor_prod,  
transform, truncate, utils, val, val1, val_ldegree, valuation, vectdegree]
```

(1)

```
The library linalg is also needed.
```

```
> with(linalg):
```

```
We load OreModules in order to use the procedure to write a D-finite partial differential system as an  
integrable connection.
```

```
> with(OreModules):
```

Consider Example 3.2 in Z. Li, F. Schwarz, and S. Tsarev. *Factoring systems of pde's with finite-dimensional solution space*, *Journal of Symbolic Computation*, 36:443--471, 2003.

```
We define the OreAlgebra (needed for OreModules):
```

```
> Alg:=DefineOreAlgebra(diff=[d1,x1],diff=[d2,x2],polynom=[x1,x2],  
comm=[]):
```

```
We give the equations of the system:
```

```
> R:=matrix(2,1,[d1^3+(x2^2+6*x1^2-6*x1*x2)/(2*x1^3-x2*x1^2)*d1^2,  
d2^3+(3*x1-2*x2)/(x1^2-x1*x2)*d2^2+(2*x1-x2)/(x1^3-x1^2*x2)*d2]);
```

(2)

$$R := \begin{bmatrix} d1^3 + \frac{(x2^2 + 6x1^2 - 6x1x2) d1^2}{2x1^3 - x2x1^2} \\ d2^3 + \frac{(3x1 - 2x2) d2^2}{x1^2 - x1x2} + \frac{(2x1 - x2) d2}{x1^3 - x2x1^2} \end{bmatrix} \quad (2)$$

We write the system as an integrable connection:

**> C:=OreModules[Connection](R,Alg);**

$$C := \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & \frac{-x1^2 + 3x1x2 - x2^2}{x1^3 - x2x1^2} & 0 & \frac{x2}{x1 - x2} \\ 0 & \frac{2x2x1^2 - 5x1x2^2 + 2x2^3}{x1^4 - x1^3x2} & 0 & \frac{-2x1x2^2 + x2^3}{x1^3 - x2x1^2} \\ 0 & \frac{2}{x1^2} & 0 & \frac{x2}{x1^2} \end{bmatrix}, \quad (3)$$

$$\begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & \frac{-x1^2 + 3x1x2 - x2^2}{x1^3 - x2x1^2} & 0 & \frac{x2}{x1 - x2} \\ 0 & \frac{-2x1 + x2}{x1^3 - x2x1^2} & 0 & \frac{-3x1 + 2x2}{x1^2 - x1x2} \end{bmatrix}$$

If we want to know the basis of the associated module in which the connection is written, we can use the procedure KBasis of OreModules:

**> OreModules[KBasis](R,Alg);**

$$[\lambda_1, d2 \lambda_1, \lambda_1 d1, d2^2 \lambda_1] \quad (4)$$

We use our procedure for computing hyperexponential solutions of the integrable connection:

**> HyperexpSols:=HyperexponentialSolutions(C, [x1, x2]);**

(5)

$$\text{HyperexpSols} := \begin{bmatrix} x1 & 1 & -e^{-\frac{x2}{x1}} x2^2 & -e^{-\frac{x2}{x1}} \\ 0 & 0 & -\frac{e^{-\frac{x2}{x1}} x2 (2 x1 - x2)}{x1} & \frac{e^{-\frac{x2}{x1}}}{x1} \\ 1 & 0 & -\frac{e^{-\frac{x2}{x1}} x2^3}{x1^2} & -\frac{e^{-\frac{x2}{x1}} x2}{x1^2} \\ 0 & 0 & -\frac{e^{-\frac{x2}{x1}} (2 x1^2 - 4 x1 x2 + x2^2)}{x1^2} & -\frac{e^{-\frac{x2}{x1}}}{x1^2} \end{bmatrix} \quad (5)$$

The rational solutions are given by the columns of the first matrix. This means the original system admits two non-zero rational solutions given by 1 and x1. The two other non-zero hyperexponential solutions are given by the second matrix. This means that the original system also admits  $\exp(-x2/x1)$  and  $x2^2 \cdot \exp(-x2/x1)$  as hyperexponential solutions.

Consider Example 3.3 in Z. Li, F. Schwarz, and S. Tsarev. *Factoring systems of pde's with finite-dimensional solution space*, *Journal of Symbolic Computation*, 36:443--471, 2003.

We define the OreAlgebra (needed for OreModules):

```
> Alg:=DefineOreAlgebra(diff=[d1,x1],diff=[d2,x2],diff=[d3,x3],
  polynom=[x1,x2,x3],comm=[]):
```

We give the equations of the system:

```
> R:=matrix(3,1,[d1^2-x1/(x1-1)*d1+1/(x1-1),d2+x1/(x2*(x1*x2-x2))*d1-
  x1/(x2*(x1*x2-x2)),d3-(2*x1*x3+1/2*x1)/(x1*x3-x3)*d1+(2*x3+1/2*x1)/
  (x1*x3-x3)]);
```

$$R := \begin{bmatrix} d1^2 - \frac{x1 d1}{x1 - 1} + \frac{1}{x1 - 1} \\ d2 + \frac{x1 d1}{x2 (x1 x2 - x2)} - \frac{x1}{x2 (x1 x2 - x2)} \\ d3 - \frac{\left(2 x1 x3 + \frac{1}{2} x1\right) d1}{x1 x3 - x3} + \frac{2 x3 + \frac{1}{2} x1}{x1 x3 - x3} \end{bmatrix} \quad (6)$$

We write the system as an integrable connection:

```
> C:=OreModules[Connection](R,Alg):
```

If we want to know the basis of the associated module in which the connection is written, we can use the procedure KBasis of OreModules:

```
> OreModules[KBasis](R,Alg);
```

$$[\lambda_1, d3 \lambda_1] \quad (7)$$

We use our procedure for computing hyperexponential solutions of the integrable connection:

**> HyperexpSols:=HyperexponentialSolutions(C, [x1, x2, x3]);**

$$\text{HyperexpSols} := \begin{bmatrix} -\frac{2 x_1 e^{-\frac{1}{x_2}}}{\sqrt{x_3}} & \frac{1}{2} e^{x_1 + 2 x_3} \\ \frac{x_1 e^{-\frac{1}{x_2}}}{x_3^{3/2}} & e^{x_1 + 2 x_3} \end{bmatrix} \quad (8)$$

The system admits two non-zero hyperexponential solutions, namely  $\exp(x_1+2x_3)$  and  $x_1/(\sqrt{x_3}) \exp(-1/x_2)$ .

Consider Example 3.4 in *Z. Li, F. Schwarz, and S. Tsarev. Factoring systems of pde's with finite-dimensional solution space, Journal of Symbolic Computation, 36:443--471, 2003.*

We define the OreAlgebra (needed for OreModules):

**> Alg:=DefineOreAlgebra(diff=[d1, x1], diff=[d2, x2], diff=[d3, x3],  
polynom=[x1, x2, x3], comm=[]):**

We give the equations of the system:

**> v:=x1^2-x1\*x3+x2^2+2\*x2\*x3+x3^2;**

$$v := x_1^2 - x_1 x_3 + x_2^2 + 2 x_2 x_3 + x_3^2 \quad (9)$$

**> w:=-2\*x2^4-8\*x3\*x2^3-12\*x2^2\*x3^2-8\*x2\*x3^3+2\*x1\*x3^3+2\*x1^3\*x2-3\*x1^2\*x3^2-4\*x1^2\*x2\*x3-2\*x1^2\*x3^2+2\*x1^4+2\*x1\*x2\*x3^2;**

$$w := -2 x_2^4 - 8 x_3 x_2^3 - 12 x_2^2 x_3^2 - 8 x_2 x_3^3 + 2 x_1 x_3^3 + 2 x_1^3 x_2 - 3 x_1^2 x_3^2 - 4 x_1^2 x_2 x_3 - 2 x_1^2 x_3^2 + x_1^4 + 2 x_1 x_2 x_3^2 \quad (10)$$

**> R:=matrix(4, 1, [  
x1\*v\*d1-x2\*v\*d2+x1\*(2\*x1\*x2+x1\*x3+x2^2)\*d3-2\*x1\*x2-x1\*x3+x1^2,  
x1\*(x1-x3)\*(2\*x2-x1+2\*x3)\*d3+(x2+x3)^2\*v\*d2+2\*x1\*v\*d2+x1\*(-2\*x2+x1-2\*x3),  
(x2+x3)^2\*v\*d2\*d3+x1\*v\*d2+2\*x1\*(x2+x3)\*(x1-x3)\*d3-2\*x1\*(x2+x3),  
(x2+x3)^2\*(x1-x3)\*v\*d3^2+w\*d3-2\*x1\*x2^2-2\*x1^2\*x2-2\*x1\*x2\*x3-x1^3-x3\*x1^2  
]);**

$$R := \begin{bmatrix} x_1 (x_1^2 - x_1 x_3 + x_2^2 + 2 x_2 x_3 + x_3^2) d_1 - x_2 (x_1^2 - x_1 x_3 + x_2^2 + 2 x_2 x_3 + x_3^2) d_2 + x_1 (2 x_1 x_2 + x_1 x_3 + x_2^2) d_3 - 2 x_1 x_2 - x_1 x_3 + x_1^2, \\ x_1 (x_1 - x_3) (2 x_2 - x_1 + 2 x_3) d_3 + (x_2 + x_3)^2 (x_1^2 - x_1 x_3 + x_2^2 + 2 x_2 x_3 + x_3^2) d_2^2 + 2 x_1 (x_1^2 - x_1 x_3 + x_2^2 + 2 x_2 x_3 + x_3^2) d_2 + x_1 (-2 x_2 + x_1 - 2 x_3), \\ (x_2 + x_3)^2 (x_1^2 - x_1 x_3 + x_2^2 + 2 x_2 x_3 + x_3^2) d_2 d_3 + x_1 (x_1^2 - x_1 x_3 + x_2^2 + 2 x_2 x_3 + x_3^2) d_2 + 2 x_1 (x_2 + x_3) (x_1 - x_3) d_3 - 2 x_1 (x_2 + x_3), \\ (x_2 + x_3)^2 (x_1 - x_3) (x_1^2 - x_1 x_3 + x_2^2 + 2 x_2 x_3 + x_3^2) d_3^2 + (-2 x_2^4 - 8 x_3 x_2^3 - 12 x_2^2 x_3^2 - 8 x_2 x_3^3 + 2 x_1 x_3^3 + 2 x_1^3 x_2 - 3 x_1^2 x_3^2 - 4 x_1^2 x_2 x_3 - 2 x_1^2 x_3^2 + x_1^4) \end{bmatrix} \quad (11)$$

$$+ 2 x_1 x_2 x_3^2) d_3 - 2 x_1 x_2^2 - 2 x_2 x_1^2 - 2 x_1 x_2 x_3 - x_1^3 - x_3 x_1^2]]$$

We write the system as an integrable connection:

**> C:=OreModules[Connection](R,Alg):**

If we want to know the basis of the associated module in which the connection is written, we can use the procedure KBasis of OreModules:

**> OreModules[KBasis](R,Alg);**

$$[\lambda_1, d_3 \lambda_1, d_2 \lambda_1] \quad (12)$$

We use our procedure for computing hyperexponential solutions of the integrable connection:

**> HyperexpSols:=HyperexponentialSolutions(C, [x1, x2, x3]);**

*HyperexpSols :=*

$$\begin{bmatrix} x_1 x_2 e^{\frac{x_1}{x_2 + x_3}} & -e^{\frac{x_1}{x_2 + x_3}} & \frac{1}{x_1 - x_3} \\ -\frac{e^{\frac{x_1}{x_2 + x_3}} x_1^2 x_2}{(x_2 + x_3)^2} & \frac{e^{\frac{x_1}{x_2 + x_3}} x_1}{(x_2 + x_3)^2} & \frac{1}{(x_1 - x_3)^2} \\ -\frac{(x_1 x_2 - x_2^2 - 2 x_2 x_3 - x_3^2) e^{\frac{x_1}{x_2 + x_3}} x_1}{(x_2 + x_3)^2} & \frac{e^{\frac{x_1}{x_2 + x_3}} x_1}{(x_2 + x_3)^2} & 0 \end{bmatrix} \quad (13)$$

The system admits one non-zero rational solution, namely  $1/(x_1-x_3)$  and two other non-zero hyperexponential solutions given by  $\exp(x_1/(x_2+x_3))$  and  $x_1*x_2*\exp(x_1/(x_2+x_3))$ .

Consider Example 4.1 in *Z. Li, F. Schwarz, and S. Tsarev. Factoring systems of pde's with finite-dimensional solution space, Journal of Symbolic Computation, 36:443--471, 2003.*

We define the OreAlgebra (needed for OreModules):

**> Alg:=DefineOreAlgebra(diff=[d1, x1], diff=[d2, x2], diff=[d3, x3],  
polynom=[x1, x2, x3], comm=[]):**

We give the equations of the system (be careful there is a typo in the fifth equation in the paper):

**> R:=matrix(6, 2, [  
(x1\*x3-x1\*x2)+(x1\*x2-1)\*d2+(1-x1\*x3)\*d3, 0, (x2\*x3-x1\*x2)+(x1\*x2-1)\*  
d1+(1-x2\*x3)\*d3, 0, -x2\*x3, d1-x2\*x3, -x1\*x3, d2-x1\*x3, d3^2-(x1\*x2+1)\*  
d3+x1\*x2, 0, -x1\*x2, d3-x1\*x2  
]);**

$$R := \begin{bmatrix} x_1 x_3 - x_1 x_2 + (-1 + x_1 x_2) d_2 + (1 - x_1 x_3) d_3 & 0 \\ x_2 x_3 - x_1 x_2 + (-1 + x_1 x_2) d_1 + (1 - x_2 x_3) d_3 & 0 \\ -x_2 x_3 & d_1 - x_2 x_3 \\ -x_1 x_3 & d_2 - x_1 x_3 \\ d_3^2 - (x_1 x_2 + 1) d_3 + x_1 x_2 & 0 \\ -x_1 x_2 & d_3 - x_1 x_2 \end{bmatrix} \quad (14)$$

We write the system as an integrable connection:

**> C:=OreModules[Connection](R,Alg);**

$$C := \left[ \begin{array}{cc} x_2 x_3 & 0 \\ x_2 x_3 & x_2 x_3 \end{array} \right], \left[ \begin{array}{cc} x_1 x_3 & 0 \\ x_1 x_3 & x_1 x_3 \end{array} \right], \left[ \begin{array}{cc} x_1 x_2 & 0 \\ x_1 x_2 & x_1 x_2 \end{array} \right] \quad (15)$$

If we want to know the basis of the associated module in which the connection is written, we can use the procedure KBasis of OreModules:

**> OreModules[KBasis](R,Alg);**

$$[\lambda_1, \lambda_2] \quad (16)$$

We use our procedure for computing hyperexponential solutions of the integrable connection:

**> HyperexpSols:=HyperexponentialSolutions(C,[x1,x2,x3]);**

$$\text{HyperexpSols} := \left[ \begin{array}{cc} e^{x_1 x_2 x_3} & 0 \\ e^{x_1 x_2 x_3} & x_1 x_2 x_3 e^{x_1 x_2 x_3} \end{array} \right] \quad (17)$$

The system admits two non-trivial hyperexponential solutions, namely  $(0, \exp(x_1 * x_2 * x_3))^T$  and  $(\exp(x_1 * x_2 * x_3), x_1 * x_2 * x_3 * \exp(x_1 * x_2 * x_3))^T$ .